

# Line Arrangements

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## 1 Arrangements

The subdivision of the plane induced by a finite set  $L$  of lines is called the **arrangement**  $\mathcal{A}(L)$ . A line arrangement is **simple** if no two lines are parallel and no three lines meet in a point. Although lines are unbounded, we can regard a line arrangement as a bounded object by (conceptually) putting a sufficiently large box around that contains all vertices. Such a box can be constructed in  $O(n \log n)$  time for  $n$  lines. (Exercise) Moreover, we can view a line arrangement as a planar graph by adding an additional vertex at “infinity”, that is incident to all rays which leave this bounding box.

**Theorem 1** *A simple arrangement  $\mathcal{A}(L)$  of  $n$  lines in  $\mathbb{R}^2$  has  $\binom{n}{2}$  vertices,  $n^2$  edges, and  $\binom{n}{2} + n + 1$  faces/cells.*

**Proof.** Since all lines intersect and all intersection points are pairwise distinct, there are  $\binom{n}{2}$  vertices.

The number of edges we prove by induction on  $n$ . For  $n = 1$  we have  $1^2 = 1$  edge. By adding one line to an arrangement of  $n - 1$  lines we split  $n - 1$  existing edges into two and introduce  $n$  new edges along the newly inserted line. Thus, there are in total  $(n - 1)^2 + 2n - 1 = n^2 - 2n + 1 + 2n - 1 = n^2$  edges.

The number  $f$  of faces can now be obtained from Euler’s formula  $v - e + f = 2$ , where  $v$  and  $e$  denote the number of vertices and edges, respectively. However, in order to apply Euler’s formula we need to consider  $\mathcal{A}(L)$  as a planar graph and take the symbolic “infinite” vertex into account. Therefore,

$$f = 2 - \left( \binom{n}{2} + 1 \right) + n^2 = 1 + \frac{1}{2}(2n^2 - n(n - 1)) = 1 + \frac{1}{2}(n^2 + n) = 1 + \binom{n}{2} + n.$$

□

The *complexity* of an arrangement is simply the total number of vertices, edges, and faces (in general, cells of all dimension).

## 2 Representation as a DCEL

We need to have a suitable representation for line arrangements that supports a variety of local operations. More specifically, it should allow to access or iterate over ...

- the (two) vertices/faces incident to an edge,
- the edges/faces incident to a vertex,
- the vertices adjacent to a vertex,
- the faces adjacent to a face.

It should also be possible to modify the structure, for instance, to

- insert a new vertex along an edge (*edge split*),
- contract or remove an edge,
- insert a new edge connecting two vertices incident to the same face (*face split*).

We use a general purpose data structure to represent planar subdivisions<sup>1</sup>, known as DCEL (doubly connected edge list) or halfedge data structure. It consists of three containers for the three entities of interest: vertices, edges, and faces. The information on how these objects are interconnected are stored at the edges mostly.

Each edge appears actually twice in the data structure, one *halfedge* for each incident face. The pair of halfedges representing the same edge of the original graph are called *twins*. Halfedges are considered oriented such that the incident face is to the left.

Each vertex and each face store a pointer to some incident halfedge. (They may also store/refer to some geometric information, e.g., coordinates of a vertex.)

Each halfedge  $e$  stores ...

1. a pointer  $e.target$  to its target vertex,
2. a pointer  $e.face$  to the incident face,
3. a pointer  $e.twin$  to its twin,
4. pointers  $e.prev$  and  $e.next$  to the previous and next halfedge in the circular sequence of halfedges around  $e.face$  (oriented anticlockwise),
5. and possibly additional information. In the case of line arrangements, one may want to store a pointer to the underlying line, for example.

How can one iterate around a face or vertex? (Needs both  $prev$  and  $next$ . The source, on the other hand, can be obtained as the twin's target in constant time.)

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<sup>1</sup>More precisely, orientable (inside/outside/left/right are well defined, no Moebius-strips) 2-manifolds (objects that look like a Euclidean disk locally). It is possible to extend this notion to objects with boundaries.

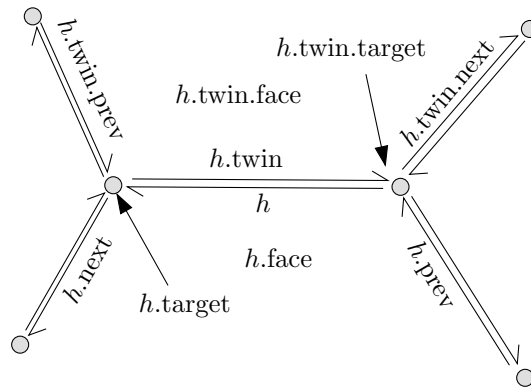


Figure 1: *The data associated to a halfedge  $h$ .*

### 3 Construction

As the complexity of a line arrangement is quadratic, there is no need to look for a sub-quadratic algorithm to construct it. We will simply construct it incrementally, inserting the lines one by one. Let  $\ell_1, \dots, \ell_n$  be the order of insertion.

At Step  $i$  of the construction, locate  $\ell_i$  in the leftmost cell of  $\mathcal{A}(\{\ell_1, \dots, \ell_{i-1}\})$  it intersects. (The halfedges leaving the infinite vertex are ordered by slope.) This takes  $O(i)$  time. Then traverse the boundary of the face  $F$  found until the halfedge  $h$  is found where  $\ell_i$  leaves  $F$ . Insert a new vertex at this point, splitting  $F$  and  $h$  and continue in the same way with the face on the other side of  $h$ .

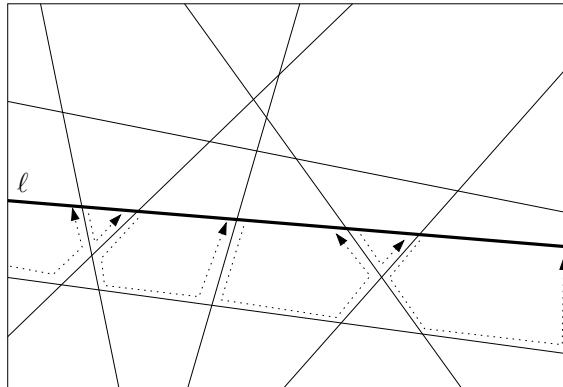


Figure 2: *Incremental construction: Insertion of a line  $\ell$ .*

What is the time needed for this traversal? The complexity of  $\mathcal{A}(\{\ell_1, \dots, \ell_{i-1}\})$  is  $\Theta(i^2)$ , but we will see that the region traversed by a single line has linear complexity only.

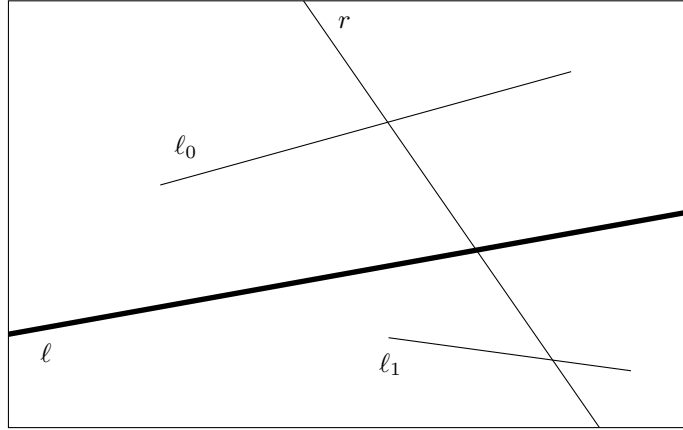
## 4 Zone Theorem

For line  $\ell$  and an arrangement  $\mathcal{A}(L)$  the **zone** of  $\ell$  in  $\mathcal{A}(L)$  is the set of faces from  $\mathcal{A}(L)$  whose closure intersects  $\ell$ .

**Theorem 2** *Given an arrangement  $\mathcal{A}(L)$  of  $n$  lines in  $\mathbb{R}^2$  and a line  $\ell$  (not necessarily from  $L$ ), the total number of edges in all cells of the zone  $Z_{\mathcal{A}(L)}(\ell)$  is at most  $6n$ .*

**Proof.** Without loss of generality suppose that  $\ell$  is horizontal and that none of the lines from  $L$  is horizontal. Split the edges of  $Z_{\mathcal{A}(L)}(\ell)$  into two groups, left-bounding and right-bounding edges (split each cell at its topmost and at its bottommost vertex). We will show that there are at most  $3n$  left-bounding edges by induction on  $n$ .

For  $n = 1$ , there is exactly one left-bounding edge in  $Z_{\mathcal{A}(L)}(\ell)$  and  $1 \leq 3n = 3$ . Assume the statement is true for  $n - 1$ .



**Figure 3:** *At most three new left-bounding edges are created by adding  $r$  to  $\mathcal{A}(L \setminus \{r\})$ .*

Consider the rightmost line  $r$  from  $L$  intersecting  $\ell$  and the arrangement  $\mathcal{A}(L \setminus \{r\})$ . By the induction hypothesis there are at most  $3n - 3$  left-bounding edges in  $Z_{\mathcal{A}(L \setminus \{r\})}(\ell)$ . Adding  $r$  back adds at most three new left-bounding edges: At most two existing left-bounding edges (call them  $\ell_0$  and  $\ell_1$ ) of the rightmost cell of the zone are intersected by  $r$  and thereby split in two, and  $r$  itself contributes one more edge to that cell. The line  $r$  cannot contribute a left-bounding edge to any cell other than the rightmost: to the left of  $r$ , the edges induced by  $r$  form right-bounding edges only and to the right of  $r$  all other cells touched by  $r$  (if any) are shielded away from  $\ell$  by one of  $\ell_0$  or  $\ell_1$ . Therefore, the total number of edges in  $Z_{\mathcal{A}(L)}(\ell)$  is bounded from above by  $3 + 3n - 3 = 3n$ .  $\square$

**Corollary 3** *The arrangement of  $n$  lines in  $\mathbb{R}^2$  can be constructed in  $O(n^2)$  time and this is optimal.*

Corresponding bounds in  $\mathbb{R}^d$ : Complexity of arrangements in  $\Theta(n^d)$ , zone of a hyperplane is  $O(n^{d-1})$ .

## 5 The Power of Duality

The real beauty and power of line arrangements becomes apparent in context of point  $\leftrightarrow$  line duality.

Recall the standard duality transform that maps a point  $p = (p_x, p_y)$  to the line  $p^* : y = p_x x - p_y$  and a line  $g : y = mx + b$  to the point  $g^* = (m, -b)$ . It is ...

- Incidence preserving:  $p \in g \iff g^* \in p^*$ .
- Order preserving:  $p$  is above  $g \iff g^*$  is above  $p^*$ .
- Another way to think of duality is in terms of the parabola  $\mathcal{P} : y = \frac{1}{2}x^2$ . For a point  $p$  on  $\mathcal{P}$ , the dual line  $p^*$  is the tangent to  $\mathcal{P}$  at  $p$ . For a point  $p$  not on  $\mathcal{P}$ , consider the vertical projection  $p'$  of  $p$  onto  $\mathcal{P}$ : the slopes of  $p^*$  and  $p'^*$  are the same, just  $p^*$  is shifted up the difference in  $y$ -coordinates.

The following problems can all be solved in  $O(n^2)$  time and space by constructing the dual arrangement.

**General position test.** Given  $n$  points in  $\mathbb{R}^2$ , are any three of them collinear? (Dual: do three lines meet in a point?)

**Minimum area triangle.** Given  $n$  points in  $\mathbb{R}^2$ , what is the minimum area triangle spanned by any three of them? For any vertex of the dual arrangement (primal: line through two points  $p$  and  $q$ ) find the closest point vertically above/below through which an input line passes (primal: closest line above/below parallel to the line through  $p$  and  $q$  that passes through an input point).

**Ham-sandwich cuts.** Given two finite sets  $R$  and  $B$  of points, construct a line that bisects both sets, that is, in either open halfplane defined by the line there are no more than  $|R|/2$  points from  $R$  and no more than  $|B|/2$  points from  $B$ .

This needs the concept of  $k$ -levels in arrangements (a point is at level  $k$  if there are at most  $k - 1$  lines below and at most  $n - k$  lines above it). Suppose wlog that no two points have the same  $x$ -coordinate. (Otherwise, rotate the plane infinitesimally.) Also suppose wlog that both  $|R|$  and  $|B|$  are odd. (Otherwise, just remove one point from the set and observe that the bisection as defined above remains valid when adding the point back.)

The median level of  $\mathcal{A}(B)$  defines the bisecting lines for  $B$  and since  $|B|$  is odd, both the leftmost and the rightmost piece of this level are defined by the same line from  $B$ , the one with median slope. Similarly for  $\mathcal{A}(R)$ . Since both lines intersect (no two points have the same  $x$ -coordinate, so no two lines have the same slope), the median levels must intersect as well, at a point whose dual corresponds to a line that bisects both  $R$  and  $B$ .

### Sorting all Angular Sequences.

**Theorem 4** *Consider a set  $P$  of  $n$  points in the plane. For a point  $q \in P$  let  $c_P(q)$  denote the circular sequence of points from  $S \setminus \{q\}$  ordered counterclockwise around  $q$  (in order as they would be encountered by a ray sweeping around  $q$ ). All  $c_P(q)$ ,  $q \in P$ , collectively can be obtained in  $O(n^2)$  time.*

**Proof.** Consider the projective dual  $P^*$  of  $P$ . An angular sweep around a point  $q \in P$  corresponds there to a traversal of the line  $q^*$  from left to right. (A collection of lines through a single point  $q$  corresponds to a collection of points on a single line  $q^*$  and slope corresponds to  $x$ -coordinate.) Clearly, the sequence of intersection points along all lines in  $P^*$  can be obtained by constructing the arrangement in  $O(n^2)$  time. In the primal plane, any such sequence corresponds to an order of the remaining points according to the slope of the connecting line; to construct the circular sequence of points as they are encountered around  $q$ , we have to split the sequence obtained from the dual into those points that are to the left of  $q$  and those that are to the right of  $q$ ; concatenating both yields the desired sequence.  $\square$