

On the Evolution of Selfish Routing

Simon Fischer

`simon.fischer@cs.uni-dortmund.de`

University of Dortmund
Dept. Computer Science 2

September 2, 2004

Introduction

Classical Game Theory

Evolutionary Game Theory

Selfish Routing

Synthesis of the Models

Dynamics in Networks

Stability

Convergence

Speed of Convergence

Approximation

Upper Bound

Lower Bound

Conclusion

Conclusion

Open Questions

References

Introduction

- Classical Game Theory
- Evolutionary Game Theory
- Selfish Routing

Synthesis of the Models

- Dynamics in Networks
- Stability
- Convergence

Speed of Convergence

- Approximation
- Upper Bound
- Lower Bound

Conclusion

- Conclusion
- Open Questions
- References

Objective 1:
Stronger Motivation

Introduction

- Classical Game Theory
- Evolutionary Game Theory
- Selfish Routing

Synthesis of the Models

- Dynamics in Networks
- Stability
- Convergence

Speed of Convergence

- Approximation
- Upper Bound
- Lower Bound

Conclusion

- Conclusion
- Open Questions
- References

Objective 1:

Stronger Motivation

Objective 2:

Hurry up!

Classical Game Theory

- ▶ We want to analyse **games** involving large networks, latency functions, many agents, ...

Classical Game Theory

- ▶ We want to analyse **games** involving large networks, latency functions, many agents, ...
- ▶ Our results are mainly concerned with **equilibria**: price of anarchy, taxes, ...

Classical Game Theory

- ▶ We want to analyse **games** involving large networks, latency functions, many agents, ...
- ▶ Our results are mainly concerned with **equilibria**: price of anarchy, taxes, ...
- ▶ In order to motivate our results we make **assumptions** about the agents: rationality, complete and accurate information etc.

Classical Game Theory

- ▶ We want to analyse **games** involving large networks, latency functions, many agents, ...
- ▶ Our results are mainly concerned with **equilibria**: price of anarchy, taxes, ...
- ▶ In order to motivate our results we make **assumptions** about the agents: rationality, complete and accurate information etc.
- ▶ Computing equilibria seems to be hard

Classical Game Theory

- ▶ We want to analyse **games** involving large networks, latency functions, many agents, ...
- ▶ Our results are mainly concerned with **equilibria**: price of anarchy, taxes, ...
- ▶ In order to motivate our results we make **assumptions** about the agents: rationality, complete and accurate information etc.
- ▶ Computing equilibria seems to be hard

Problem

How do we justify these assumptions when it comes to games related to something as mind-bogglingly large and inscrutable as the Internet?

Evolutionary Game Theory – Motivation

Goal

Make weaker assumptions about the agents.

Evolutionary Game Theory – Motivation

Goal

Make weaker assumptions about the agents.

- ▶ Model the *dynamics* of the population vector $\mathbf{x}(t)$.

Evolutionary Game Theory – Motivation

Goal

Make weaker assumptions about the agents.

- ▶ Model the *dynamics* of the population vector $\mathbf{x}(t)$.
- ▶ Several models:

Evolutionary Game Theory – Motivation

Goal

Make weaker assumptions about the agents.

- ▶ Model the *dynamics* of the population vector $\mathbf{x}(t)$.
- ▶ Several models:
 - ▶ Agents play against random partner, observe payoff difference, and imitate their opponents' strategy with probability „proportional“ to this difference.

Evolutionary Game Theory – Motivation

Goal

Make weaker assumptions about the agents.

- ▶ Model the *dynamics* of the population vector $\mathbf{x}(t)$.
- ▶ Several models:
 - ▶ Agents play against random partner, observe payoff difference, and imitate their opponents' strategy with probability „proportional“ to this difference.
 - ▶ Agents have a random aspiration level. Whenever they fall short of this level, they adopt a random strategy.

Evolutionary Game Theory – Motivation

Goal

Make weaker assumptions about the agents.

- ▶ Model the *dynamics* of the population vector $\mathbf{x}(t)$.
- ▶ Several models:
 - ▶ Agents play against random partner, observe payoff difference, and imitate their opponents' strategy with probability „proportional“ to this difference.
 - ▶ Agents have a random aspiration level. Whenever they fall short of this level, they adopt a random strategy.
- ▶ Both models lead to the same dynamics!

Replicator dynamics

Definition (Replicator dynamics)

$$\dot{x}_i = \lambda(\mathbf{x}) \cdot x_i \cdot ((\mathbf{Ax})_i - \mathbf{x} \cdot \mathbf{Ax})$$

Replicator dynamics

Definition (Replicator dynamics)

$$\dot{x}_i = \lambda(\mathbf{x}) \cdot x_i \cdot ((\mathbf{Ax})_i - \mathbf{x} \cdot \mathbf{Ax})$$

- ▶ Desirable properties:

Replicator dynamics

Definition (Replicator dynamics)

$$\dot{x}_i = \lambda(\mathbf{x}) \cdot x_i \cdot ((\mathbf{Ax})_i - \mathbf{x} \cdot \mathbf{Ax})$$

- ▶ Desirable properties:
 - ▶ *homogeneity*: $\dot{x}_i = x_i \cdot g_i(\mathbf{x})$.

Replicator dynamics

Definition (Replicator dynamics)

$$\dot{x}_i = \lambda(\mathbf{x}) \cdot x_i \cdot ((\mathbf{Ax})_i - \mathbf{x} \cdot \mathbf{Ax})$$

► Desirable properties:

- *homogeneity*: $\dot{x}_i = x_i \cdot g_i(\mathbf{x})$.
- *monotonicity*: $(\mathbf{Ax})_i > (\mathbf{Ax})_j \Leftrightarrow g_i(\mathbf{x}) > g_j(\mathbf{x})$

Replicator dynamics

Definition (Replicator dynamics)

$$\dot{x}_i = \lambda(\mathbf{x}) \cdot x_i \cdot ((\mathbf{Ax})_i - \mathbf{x} \cdot \mathbf{Ax})$$

► Desirable properties:

- ▶ *homogeneity*: $\dot{x}_i = x_i \cdot g_i(\mathbf{x})$.
- ▶ *monotonicity*: $(\mathbf{Ax})_i > (\mathbf{Ax})_j \Leftrightarrow g_i(\mathbf{x}) > g_j(\mathbf{x})$
- ▶ *aggregate monotonicity*: $\mathbf{y} \cdot \mathbf{Ax} > \mathbf{z} \cdot \mathbf{Ax} \Leftrightarrow \mathbf{y} \cdot \mathbf{g}(\mathbf{x}) > \mathbf{z} \cdot \mathbf{g}(\mathbf{x})$

Replicator dynamics

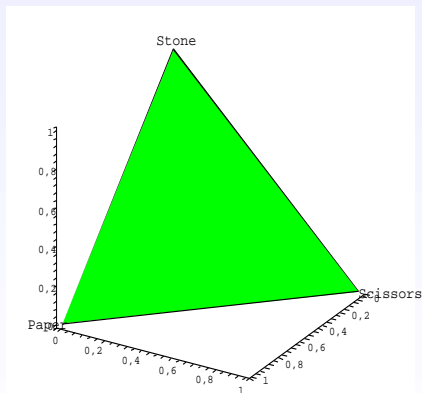
Definition (Replicator dynamics)

$$\dot{x}_i = \lambda(\mathbf{x}) \cdot x_i \cdot ((\mathbf{Ax})_i - \mathbf{x} \cdot \mathbf{Ax})$$

- ▶ Desirable properties:
 - ▶ *homogeneity*: $\dot{x}_i = x_i \cdot g_i(\mathbf{x})$.
 - ▶ *monotonicity*: $(\mathbf{Ax})_i > (\mathbf{Ax})_j \Leftrightarrow g_i(\mathbf{x}) > g_j(\mathbf{x})$
 - ▶ *aggregate monotonicity*: $\mathbf{y} \cdot \mathbf{Ax} > \mathbf{z} \cdot \mathbf{Ax} \Leftrightarrow \mathbf{y} \cdot \mathbf{g}(\mathbf{x}) > \mathbf{z} \cdot \mathbf{g}(\mathbf{x})$
- ▶ All dynamics having these properties can be represented this way!

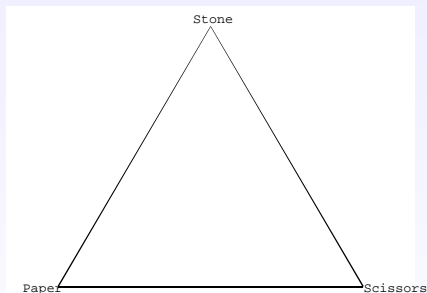
Example: Paper-Scissors-Stone

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 2 \\ 2 & 0 & 1 \end{bmatrix}$$



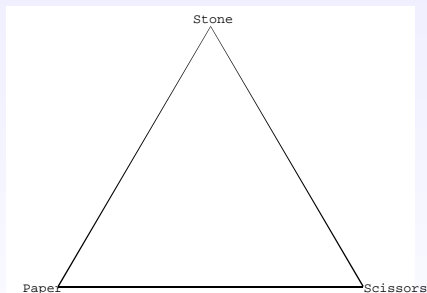
Example: Paper-Scissors-Stone

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 2 \\ 2 & 0 & 1 \end{bmatrix}$$



Example: Paper-Scissors-Stone

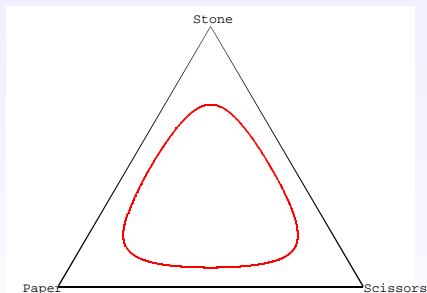
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 2 \\ 2 & 0 & 1 \end{bmatrix}$$



- ▶ Where is the Nash equilibrium? What should one expect?

Example: Paper-Scissors-Stone

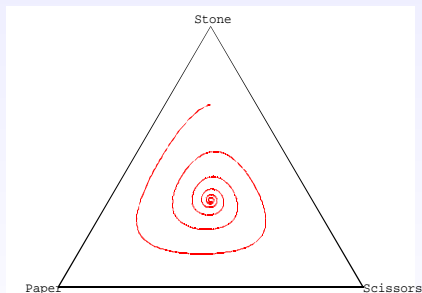
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 2 \\ 2 & 0 & 1 \end{bmatrix}$$



- ▶ Where is the Nash equilibrium? What should one expect?
- ▶ Stable orbit for the standard case

Example: Paper-Scissors-Stone

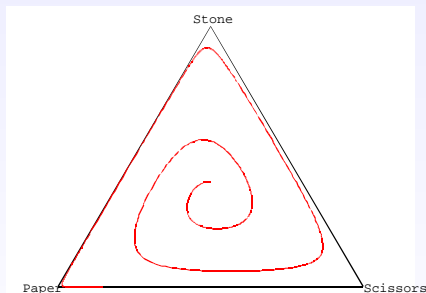
$$A = \begin{bmatrix} 1 & 2 + \epsilon & 0 \\ 0 & 1 & 2 + \epsilon \\ 2 + \epsilon & 0 & 1 \end{bmatrix}$$



- ▶ Where is the Nash equilibrium? What should one expect?
- ▶ Stable orbit for the standard case
- ▶ Convergent for $\epsilon > 0$

Example: Paper-Scissors-Stone

$$A = \begin{bmatrix} 1 & 2 - \epsilon & 0 \\ 0 & 1 & 2 - \epsilon \\ 2 - \epsilon & 0 & 1 \end{bmatrix}$$



- ▶ Where is the Nash equilibrium? What should one expect?
- ▶ Stable orbit for the standard case
- ▶ Convergent for $\epsilon > 0$
- ▶ Divergent for $\epsilon < 0$

Selfish Routing

- ▶ Network $G = (V, E)$, latency functions defined for all edges
 $l_e : [0, 1] \mapsto \mathbb{R}_0^+$.

Selfish Routing

- ▶ Network $G = (V, E)$, latency functions defined for all edges $l_e : [0, 1] \mapsto \mathbb{R}_0^+$.
- ▶ Commodities \mathcal{I} with demands d_i , s_i - t_i -paths P_i .

Selfish Routing

- ▶ Network $G = (V, E)$, latency functions defined for all edges $l_e : [0, 1] \mapsto \mathbb{R}_0^+$.
- ▶ Commodities \mathcal{I} with demands d_i , s_i - t_i -paths P_i .
- ▶ Flow on path p is x_p ; flow on edge $e \in E$ is x_e .

$$l_p(\mathbf{x}) = \sum_{e \in p} l_e(x_e)$$

Selfish Routing

- ▶ Network $G = (V, E)$, latency functions defined for all edges $l_e : [0, 1] \mapsto \mathbb{R}_0^+$.
- ▶ Commodities \mathcal{I} with demands d_i , s_i - t_i -paths P_i .
- ▶ Flow on path p is x_p ; flow on edge $e \in E$ is x_e .

$$l_p(\mathbf{x}) = \sum_{e \in p} l_e(x_e)$$

Definition (Wardrop equilibrium)

A flow \mathbf{x} is at a Wardrop equilibrium iff for all $i \in \mathcal{I}$ and all $p, p' \in P_i$ with $x_p > 0$ it holds that $l_p(\mathbf{x}) \leq l_{p'}(\mathbf{x})$.

Selfish Routing and Game Theory

- ▶ What has been done so far?

Selfish Routing and Game Theory

- ▶ What has been done so far?
 - ▶ equilibria

Selfish Routing and Game Theory

- ▶ What has been done so far?
 - ▶ equilibria
 - ▶ *price of anarchy, coordination ratio*

Selfish Routing and Game Theory

- ▶ What has been done so far?
 - ▶ equilibria
 - ▶ *price of anarchy*, *coordination ratio*
 - ▶ pricing, taxes

Selfish Routing and Game Theory

- ▶ What has been done so far?
 - ▶ equilibria
 - ▶ *price of anarchy*, *coordination ratio*
 - ▶ pricing, taxes
 - ▶ ...

Selfish Routing and Game Theory

- ▶ What has been done so far?
 - ▶ equilibria
 - ▶ *price of anarchy*, *coordination ratio*
 - ▶ pricing, taxes
 - ▶ ...
- ▶ Here, we are especially interested in **dynamical** properties.

Synthesis of Models

- ▶ Replace average payoff $\mathbf{x} \cdot \mathbf{A} \mathbf{x}$ by $\bar{l}(\mathbf{x})$
- ▶ Replace payoff $(\mathbf{A} \mathbf{x})_p$ by latency $-l_p(\mathbf{x})$

Definition (Network dynamics)

$$\dot{x}_p = \lambda(\mathbf{x}) \cdot x_p \cdot (\bar{l}(\mathbf{x}) - l_p(\mathbf{x}))$$

Synthesis of Models

- ▶ Replace average payoff $\mathbf{x} \cdot \mathbf{A} \mathbf{x}$ by $\bar{l}(\mathbf{x})$
- ▶ Replace payoff $(\mathbf{A} \mathbf{x})_p$ by latency $-l_p(\mathbf{x})$

Definition (Network dynamics)

$$\dot{x}_p = \lambda_{i(p)}(\mathbf{x}) \cdot x_p \cdot (\bar{l}_{i(p)}(\mathbf{x}) - l_p(\mathbf{x}))$$

Synthesis of Models

- ▶ Replace average payoff $\mathbf{x} \cdot \mathbf{A} \mathbf{x}$ by $\bar{l}(\mathbf{x})$
- ▶ Replace payoff $(\mathbf{A} \mathbf{x})_p$ by latency $-l_p(\mathbf{x})$

Definition (Network dynamics)

$$\dot{x}_p = \lambda_{i(p)}(\mathbf{x}) \cdot x_p \cdot (\bar{l}_{i(p)}(\mathbf{x}) - l_p(\mathbf{x}))$$

- ▶ Choose $\lambda_i(\mathbf{x}) = 1/\bar{l}_i(\mathbf{x})$.

Synthesis of Models

- ▶ Replace average payoff $\mathbf{x} \cdot \mathbf{A} \mathbf{x}$ by $\bar{l}(\mathbf{x})$
- ▶ Replace payoff $(\mathbf{A} \mathbf{x})_p$ by latency $-l_p(\mathbf{x})$

Definition (Network dynamics)

$$\dot{x}_p = x_p \cdot \frac{\bar{l}_{i(p)}(\mathbf{x}) - l_p(\mathbf{x})}{\bar{l}_{i(p)}(\mathbf{x})}$$

- ▶ Choose $\lambda_i(\mathbf{x}) = 1/\bar{l}_i(\mathbf{x})$.

Synthesis of Models

- ▶ Replace average payoff $\mathbf{x} \cdot \mathbf{A} \mathbf{x}$ by $\bar{l}(\mathbf{x})$
- ▶ Replace payoff $(\mathbf{A} \mathbf{x})_p$ by latency $-l_p(\mathbf{x})$

Definition (Network dynamics)

$$\dot{x}_p = x_p \cdot \frac{\bar{l}_{i(p)}(\mathbf{x}) - l_p(\mathbf{x})}{\bar{l}_{i(p)}(\mathbf{x})}$$

- ▶ Choose $\lambda_i(\mathbf{x}) = 1/\bar{l}_i(\mathbf{x})$.
- ▶ **Proposition:** Solutions of this DE do not leave the simplex.

Stability

- ▶ Need to define stability in a new way.

Stability

- ▶ Need to define stability in a new way.

Definition (evolutionary stable)

A strategy x is evolutionary stable, iff it is at a Nash equilibrium and for all best replies y it holds that $x \cdot l(y) < y \cdot l(y)$.

Stability

- ▶ Need to define stability in a new way.

Definition (evolutionary stable)

A strategy x is evolutionary stable, iff it is at a Nash equilibrium and for all best replies y it holds that $x \cdot l(y) < y \cdot l(y)$.

- ▶ **Best reply:** No other strategy yields a better payoff.

Stability

- ▶ Need to define stability in a new way.

Definition (evolutionary stable)

A strategy x is evolutionary stable, iff it is at a Nash equilibrium and for all best replies y it holds that $x \cdot l(y) < y \cdot l(y)$.

- ▶ **Best reply:** No other strategy yields a better payoff.

Proposition

For strictly increasing latency functions and single-commodity networks any Nash equilibrium is also evolutionary stable.

▶ Skip proof

Stability – Proof

- ▶ In a Wardrop equilibrium \mathbf{x} , all latencies of used paths are equal, implying $\mathbf{x} \cdot \mathbf{l}(\mathbf{x}) \leq \mathbf{y} \cdot \mathbf{l}(\mathbf{x})$ and

$$\mathbf{y} \cdot \mathbf{l}(\mathbf{y}) \geq \mathbf{x} \cdot \mathbf{l}(\mathbf{x}) + \sum_{e \in E} y_e (l_e(\mathbf{y}) - l_e(\mathbf{x})).$$

Stability – Proof

- ▶ In a Wardrop equilibrium \mathbf{x} , all latencies of used paths are equal, implying $\mathbf{x} \cdot \mathbf{l}(\mathbf{x}) \leq \mathbf{y} \cdot \mathbf{l}(\mathbf{x})$ and

$$\mathbf{y} \cdot \mathbf{l}(\mathbf{y}) \geq \mathbf{x} \cdot \mathbf{l}(\mathbf{x}) + \sum_{e \in E} y_e (l_e(\mathbf{y}) - l_e(\mathbf{x})).$$

- ▶ For each edge there are three cases:

Stability – Proof

- ▶ In a Wardrop equilibrium \mathbf{x} , all latencies of used paths are equal, implying $\mathbf{x} \cdot \mathbf{l}(\mathbf{x}) \leq \mathbf{y} \cdot \mathbf{l}(\mathbf{x})$ and

$$\mathbf{y} \cdot \mathbf{l}(\mathbf{y}) \geq \mathbf{x} \cdot \mathbf{l}(\mathbf{x}) + \sum_{e \in E} y_e (l_e(\mathbf{y}) - l_e(\mathbf{x})).$$

- ▶ For each edge there are three cases:
 1. $y_e > x_e$. Then $\Rightarrow l_e(\mathbf{y}) > l_e(\mathbf{x})$.

Stability – Proof

- ▶ In a Wardrop equilibrium \mathbf{x} , all latencies of used paths are equal, implying $\mathbf{x} \cdot \mathbf{l}(\mathbf{x}) \leq \mathbf{y} \cdot \mathbf{l}(\mathbf{x})$ and

$$\mathbf{y} \cdot \mathbf{l}(\mathbf{y}) \geq \mathbf{x} \cdot \mathbf{l}(\mathbf{x}) + \sum_{e \in E} y_e (l_e(\mathbf{y}) - l_e(\mathbf{x})).$$

- ▶ For each edge there are three cases:
 1. $y_e > x_e$. Then $\Rightarrow l_e(\mathbf{y}) > l_e(\mathbf{x})$.
 2. $y_e < x_e$. Then $\Rightarrow l_e(\mathbf{y}) < l_e(\mathbf{x})$.

Stability – Proof

- ▶ In a Wardrop equilibrium \mathbf{x} , all latencies of used paths are equal, implying $\mathbf{x} \cdot \mathbf{l}(\mathbf{x}) \leq \mathbf{y} \cdot \mathbf{l}(\mathbf{x})$ and

$$\mathbf{y} \cdot \mathbf{l}(\mathbf{y}) \geq \mathbf{x} \cdot \mathbf{l}(\mathbf{x}) + \sum_{e \in E} y_e (l_e(\mathbf{y}) - l_e(\mathbf{x})).$$

- ▶ For each edge there are three cases:
 1. $y_e > x_e$. Then $\Rightarrow l_e(\mathbf{y}) > l_e(\mathbf{x})$.
 2. $y_e < x_e$. Then $\Rightarrow l_e(\mathbf{y}) < l_e(\mathbf{x})$.
 3. $y_e = x_e$. Then $\Rightarrow l_e(\mathbf{y}) = l_e(\mathbf{x})$.

Stability – Proof

- ▶ In a Wardrop equilibrium \mathbf{x} , all latencies of used paths are equal, implying $\mathbf{x} \cdot \mathbf{l}(\mathbf{x}) \leq \mathbf{y} \cdot \mathbf{l}(\mathbf{x})$ and

$$\mathbf{y} \cdot \mathbf{l}(\mathbf{y}) \geq \mathbf{x} \cdot \mathbf{l}(\mathbf{x}) + \sum_{e \in E} y_e (l_e(\mathbf{y}) - l_e(\mathbf{x})).$$

- ▶ For each edge there are three cases:
 1. $y_e > x_e$. Then $\Rightarrow l_e(\mathbf{y}) > l_e(\mathbf{x})$.
 2. $y_e < x_e$. Then $\Rightarrow l_e(\mathbf{y}) < l_e(\mathbf{x})$.
 3. $y_e = x_e$. Then $\Rightarrow l_e(\mathbf{y}) = l_e(\mathbf{x})$.
- ▶ In all cases, $y_e (l_e(\mathbf{y}) - l_e(\mathbf{x})) \geq x_e (l_e(\mathbf{y}) - l_e(\mathbf{x}))$, at least once with strict inequality.

Stability – Proof

- ▶ In a Wardrop equilibrium \mathbf{x} , all latencies of used paths are equal, implying $\mathbf{x} \cdot \mathbf{l}(\mathbf{x}) \leq \mathbf{y} \cdot \mathbf{l}(\mathbf{x})$ and

$$\mathbf{y} \cdot \mathbf{l}(\mathbf{y}) \geq \mathbf{x} \cdot \mathbf{l}(\mathbf{x}) + \sum_{e \in E} y_e (l_e(\mathbf{y}) - l_e(\mathbf{x})).$$

- ▶ For each edge there are three cases:
 1. $y_e > x_e$. Then $\Rightarrow l_e(\mathbf{y}) > l_e(\mathbf{x})$.
 2. $y_e < x_e$. Then $\Rightarrow l_e(\mathbf{y}) < l_e(\mathbf{x})$.
 3. $y_e = x_e$. Then $\Rightarrow l_e(\mathbf{y}) = l_e(\mathbf{x})$.
- ▶ In all cases, $y_e (l_e(\mathbf{y}) - l_e(\mathbf{x})) \geq x_e (l_e(\mathbf{y}) - l_e(\mathbf{x}))$, at least once with strict inequality.
- ▶ Altogether,

$$\mathbf{y} \cdot \mathbf{l}(\mathbf{y}) > \mathbf{x} \cdot \mathbf{l}(\mathbf{x}) + \sum_{e \in E} x_e (l_e(\mathbf{y}) - l_e(\mathbf{x})) = \mathbf{x} \cdot \mathbf{l}(\mathbf{y}). \quad \square$$

Convergence

- ▶ Consider the single-commodity case.

Convergence

- ▶ Consider the single-commodity case.
- ▶ The replicator dynamics does not find any initially unused strategies.

Convergence

- ▶ Consider the single-commodity case.
- ▶ The replicator dynamics does not find any initially unused strategies.
- ▶ Therefore, we restrict the strategy space to the set of paths P' , which is the support of the initial population.

Convergence

- ▶ Consider the single-commodity case.
- ▶ The replicator dynamics does not find any initially unused strategies.
- ▶ Therefore, we restrict the strategy space to the set of paths P' , which is the support of the initial population.

Proposition

Solutions of the replicator dynamics with initial population \mathbf{x}_0 converge against a restricted Wardrop equilibrium \mathbf{x}^ w. r. t. \mathbf{x}_0 , i. e. $\lim_{t \rightarrow \infty} \|\mathbf{x}(t) - \mathbf{x}^*\| = 0$.*

▶ Skip proof

Convergence – Proof

- ▶ Use conditional entropy as a potential function:

$$H_{\mathbf{x}^*}(\mathbf{x}) := \sum_{p \in \mathcal{P}} x_p^* \ln \frac{x_p^*}{x_p}.$$

Convergence – Proof

- ▶ Use conditional entropy as a potential function:

$$H_{\mathbf{x}^*}(\mathbf{x}) := \sum_{p \in P} x_p^* \ln \frac{x_p^*}{x_p}.$$

- ▶ It holds that $\|\mathbf{x}^* - \mathbf{x}\|^2 \leq H_{\mathbf{x}^*}(\mathbf{x})$.

Convergence – Proof

- ▶ Use conditional entropy as a potential function:

$$H_{\mathbf{x}^*}(\mathbf{x}) := \sum_{p \in \mathcal{P}} x_p^* \ln \frac{x_p^*}{x_p}.$$

- ▶ It holds that $\|\mathbf{x}^* - \mathbf{x}\|^2 \leq H_{\mathbf{x}^*}(\mathbf{x})$.
- ▶ Calculate the derivative $\dot{H}_{\mathbf{x}^*}(\mathbf{x}) = - \sum_{p \in \mathcal{P}} x_p^* \frac{\dot{x}_p}{x_p}$.

Convergence – Proof

- ▶ Use conditional entropy as a potential function:

$$H_{\mathbf{x}^*}(\mathbf{x}) := \sum_{p \in \mathcal{P}} x_p^* \ln \frac{x_p^*}{x_p}.$$

- ▶ It holds that $\|\mathbf{x}^* - \mathbf{x}\|^2 \leq H_{\mathbf{x}^*}(\mathbf{x})$.
- ▶ Calculate the derivative $\dot{H}_{\mathbf{x}^*}(\mathbf{x}) = - \sum_{p \in \mathcal{P}} x_p^* \frac{\dot{x}_p}{x_p}$.
- ▶ Substituting the replicator dynamics yields $\dot{H}_{\mathbf{x}^*}(\mathbf{x}) = \lambda(\mathbf{x}) \cdot (\mathbf{x}^* - \mathbf{x}) \cdot \mathbf{1}(\mathbf{x})$.

Convergence – Proof

- ▶ Use conditional entropy as a potential function:

$$H_{\mathbf{x}^*}(\mathbf{x}) := \sum_{p \in \mathcal{P}} x_p^* \ln \frac{x_p^*}{x_p}.$$

- ▶ It holds that $\|\mathbf{x}^* - \mathbf{x}\|^2 \leq H_{\mathbf{x}^*}(\mathbf{x})$.
- ▶ Calculate the derivative $\dot{H}_{\mathbf{x}^*}(\mathbf{x}) = - \sum_{p \in \mathcal{P}} x_p^* \frac{\dot{x}_p}{x_p}$.
- ▶ Substituting the replicator dynamics yields $\dot{H}_{\mathbf{x}^*}(\mathbf{x}) = \lambda(\mathbf{x}) \cdot (\mathbf{x}^* - \mathbf{x}) \cdot \mathbf{1}(\mathbf{x})$.
- ▶ This difference is negative because of evolutionary stability. □

Approximating Equilibria

- ▶ Need to define approximations.

Approximating Equilibria

- ▶ Need to define approximations.
- ▶ Euclidian distance not suitable here.

Approximating Equilibria

- ▶ Need to define approximations.
- ▶ Euclidian distance not suitable here.
- ▶ We do not want to wait for minorities, since they can increase time of convergence arbitrarily.

Approximating Equilibria

- ▶ Need to define approximations.
- ▶ Euclidian distance not suitable here.
- ▶ We do not want to wait for minorities, since they can increase time of convergence arbitrarily.

Definition (ϵ -equilibrium)

Let P_ϵ be the set of all paths with latency $(1 + \epsilon) \cdot \bar{l}$ or above. Let x_ϵ be the number of agents on these paths. A population is at an ϵ -equilibrium, iff $x_\epsilon \leq \epsilon$.

Upper Bound – Potential Function

Theorem

For strictly increasing latency functions and single commodity networks the replicator dynamics reaches an ϵ -equilibrium in time $\mathcal{O}(\epsilon^{-3} \cdot \ln(l_{\max}/l^))$.*

▶ Skip proof

Upper Bound – Potential Function

Theorem

For strictly increasing latency functions and single commodity networks the replicator dynamics reaches an ϵ -equilibrium in time $\mathcal{O}(\epsilon^{-3} \cdot \ln(l_{\max}/l^))$.*

▶ Skip proof

- ▶ Use generalisation of the Rosenthal's potential function:

$$\Phi(\mathbf{x}) := \left(\sum_{e \in E} \int_0^{x_e} l_e(x) dx \right) + l^*.$$

Upper Bound – Potential Function

Theorem

For strictly increasing latency functions and single commodity networks the replicator dynamics reaches an ϵ -equilibrium in time $\mathcal{O}(\epsilon^{-3} \cdot \ln(l_{\max}/l^))$.*

▶ Skip proof

- ▶ Use generalisation of the Rosenthal's potential function:

$$\Phi(\mathbf{x}) := \left(\sum_{e \in E} \int_0^{x_e} l_e(x) dx \right) + l^*.$$

- ▶ Calculate derivative and plug in replicator dynamics:

$$\dot{\Phi} = \lambda(\mathbf{x}) \left(\bar{l}(\mathbf{x})^2 - \sum_{p \in P} x_p l_p(\mathbf{x})^2 \right) < 0.$$

Upper Bound – Some Estimates

- ▶ At least ϵ agents have latency of $(1 + \epsilon)\bar{l}$ or above.

Upper Bound – Some Estimates

- ▶ At least ϵ agents have latency of $(1 + \epsilon)\bar{l}$ or above.
- ▶ Decrease of potential is minimal when other agents are distributed uniformly among the remaining strategies.

Upper Bound – Some Estimates

- ▶ At least ϵ agents have latency of $(1 + \epsilon)\bar{l}$ or above.
- ▶ Decrease of potential is minimal when other agents are distributed uniformly among the remaining strategies.
- ▶ This yields $\dot{\Phi} \leq -\epsilon^3 \cdot \bar{l}(\mathbf{x})/2$.

Upper Bound – Some Estimates

- ▶ At least ϵ agents have latency of $(1 + \epsilon)\bar{l}$ or above.
- ▶ Decrease of potential is minimal when other agents are distributed uniformly among the remaining strategies.
- ▶ This yields $\dot{\Phi} \leq -\epsilon^3 \cdot \bar{l}(\mathbf{x})/2$.
- ▶ Since $\bar{l} \geq \sum_e \int_0^{x_e} l_e(x) dx$ and $\bar{l} \geq l^*$, it holds that $2 \cdot \bar{l}(\mathbf{x}) \geq \Phi$ and therefore

$$\dot{\Phi} \leq -\epsilon^3 \Phi/4.$$

Upper Bound – Solution of the DE

- ▶ Solving the differential inequality

$$\dot{\Phi} \leq -\epsilon^3 \Phi / 4$$

we get

$$\Phi(t) \leq \Phi(0)e^{-\epsilon^3/4 \cdot t}.$$

Upper Bound – Solution of the DE

- ▶ Solving the differential inequality

$$\dot{\Phi} \leq -\epsilon^3 \Phi / 4$$

we get

$$\Phi(t) \leq \Phi(0)e^{-\epsilon^3/4 \cdot t}.$$

- ▶ Since $\Phi \geq l^*$ and $\Phi(0) \leq 2 \cdot l_{\max}$, Φ reaches its minimum in time at most

$$t = \mathcal{O}\left(\epsilon^{-3} \cdot \ln \frac{l_{\max}}{l^*}\right).$$



Lower Bound

- ▶ In what respect are the assumptions of the analysis of the upper bound pessimistic?

Lower Bound

- ▶ In what respect are the assumptions of the analysis of the upper bound pessimistic?
 - ▶ The estimate $\bar{l} \geq \sum_{e \in E} \int_0^{x_e} l_e(x) dx$ holds with equality when latency functions are constant.

Lower Bound

- ▶ In what respect are the assumptions of the analysis of the upper bound pessimistic?
 - ▶ The estimate $\bar{l} \geq \sum_{e \in E} \int_0^{x_e} l_e(x) dx$ holds with equality when latency functions are constant.
 - ▶ We assume that always exactly ϵ agents are by a factor of exactly $1 + \epsilon$ worse than the average.

Lower Bound

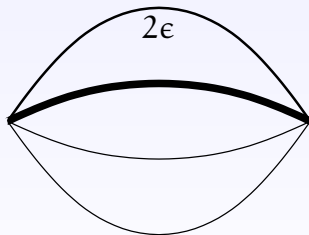
- ▶ In what respect are the assumptions of the analysis of the upper bound pessimistic?
 - ▶ The estimate $\bar{l} \geq \sum_{e \in E} \int_0^{x_e} l_e(x) dx$ holds with equality when latency functions are constant.
 - ▶ We assume that always exactly ϵ agents are by a factor of exactly $1 + \epsilon$ worse than the average.
- ▶ No more estimates.

Lower Bound

- ▶ In what respect are the assumptions of the analysis of the upper bound pessimistic?
 - ▶ The estimate $\bar{l} \geq \sum_{e \in E} \int_0^{x_e} l_e(x) dx$ holds with equality when latency functions are constant.
 - ▶ We assume that always exactly ϵ agents are by a factor of exactly $1 + \epsilon$ worse than the average.
- ▶ No more estimates.
- ▶ Can we find a scenario where all inequalities hold with equality?

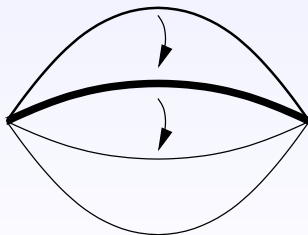
Lower Bound – Construction

- ▶ n parallel links $\{0, \dots, n-1\}$.
- ▶ Link i has constant latency $(1 + c\epsilon)^{-i}$.
- ▶ Start with $x_0 = 2\epsilon$, $x_1 = 1 - 2\epsilon - \gamma$, $\sum_{i=2}^{n-1} x_i = r$ for some very small rest γ .
- ▶ Link 1 dominates the average, $x_\epsilon = x_0 > \epsilon$.



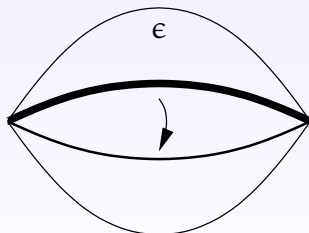
Lower Bound – Construction

- ▶ n parallel links $\{0, \dots, n-1\}$.
- ▶ Link i has constant latency $(1 + c\epsilon)^{-i}$.
- ▶ Start with $x_0 = 2\epsilon$, $x_1 = 1 - 2\epsilon - \gamma$, $\sum_{i=2}^{n-1} x_i = r$ for some very small rest γ .
- ▶ Link 1 dominates the average, $x_\epsilon = x_0 > \epsilon$.



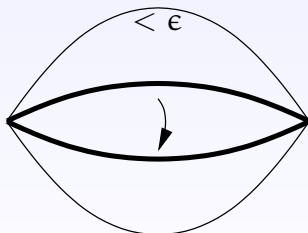
Lower Bound – Construction

- ▶ n parallel links $\{0, \dots, n-1\}$.
- ▶ Link i has constant latency $(1 + c\epsilon)^{-i}$.
- ▶ Start with $x_0 = 2\epsilon$, $x_1 = 1 - 2\epsilon - \gamma$, $\sum_{i=2}^{n-1} x_i = r$ for some very small rest γ .
- ▶ Link 1 dominates the average, $x_\epsilon = x_0 > \epsilon$.



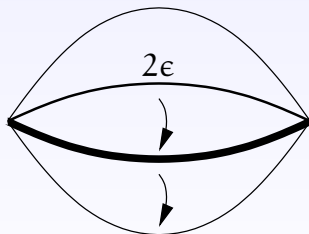
Lower Bound – Construction

- ▶ n parallel links $\{0, \dots, n-1\}$.
- ▶ Link i has constant latency $(1 + c\epsilon)^{-i}$.
- ▶ Start with $x_0 = 2\epsilon$, $x_1 = 1 - 2\epsilon - \gamma$, $\sum_{i=2}^{n-1} x_i = r$ for some very small rest γ .
- ▶ Link 1 dominates the average, $x_\epsilon = x_0 > \epsilon$.



Lower Bound – Construction

- ▶ n parallel links $\{0, \dots, n-1\}$.
- ▶ Link i has constant latency $(1 + c\epsilon)^{-i}$.
- ▶ Start with $x_0 = 2\epsilon$, $x_1 = 1 - 2\epsilon - \gamma$, $\sum_{i=2}^{n-1} x_i = r$ for some very small rest γ .
- ▶ Link 1 dominates the average, $x_\epsilon = x_0 > \epsilon$.



Lower Bound – Analysis

- ▶ For all (except the first) links we need time $\Omega(1/\epsilon)$.

Lower Bound – Analysis

- ▶ For all (except the first) links we need time $\Omega(1/\epsilon)$.
- ▶ We calculate the number of links n , which can be inserted into the network for some fixed $r = l_{\max}/l^* = (1 + c\epsilon)^{n-1}$.

Lower Bound – Analysis

- ▶ For all (except the first) links we need time $\Omega(1/\epsilon)$.
- ▶ We calculate the number of links n , which can be inserted into the network for some fixed $r = l_{\max}/l^* = (1 + c\epsilon)^{n-1}$.
- ▶ Solving this yields $n = \frac{\ln r}{\ln(1+c\epsilon)} + 1 \geq c^{-1}\epsilon^{-1} \ln r$.

Lower Bound – Analysis

- ▶ For all (except the first) links we need time $\Omega(1/\epsilon)$.
- ▶ We calculate the number of links n , which can be inserted into the network for some fixed $r = l_{\max}/l^* = (1 + c\epsilon)^{n-1}$.
- ▶ Solving this yields $n = \frac{\ln r}{\ln(1+c\epsilon)} + 1 \geq c^{-1}\epsilon^{-1} \ln r$.

Theorem

For any fixed value of $r = \frac{l_{\max}}{l^}$ there exists a network, in which the time of reaching an ϵ -equilibrium is at least $\Omega(\epsilon^{-2} \cdot \ln r)$.*

Some remarks

- ▶ This analysis is fairly robust – agents are not required to behave exactly as described by the dynamics.

Some remarks

- ▶ This analysis is fairly robust – agents are not required to behave exactly as described by the dynamics.
 - ▶ We only require an ϵ -fraction of the agents to improve their strategy when they are above $(1 + \epsilon)\bar{l}$

Some remarks

- ▶ This analysis is fairly robust – agents are not required to behave exactly as described by the dynamics.
 - ▶ We only require an ϵ -fraction of the agents to improve their strategy when they are above $(1 + \epsilon)\bar{l}$
 - ▶ One might chose λ in a different way, e. g. the prob. to change $\frac{l_i - l_j}{l_i}$

Some remarks

- ▶ This analysis is fairly robust – agents are not required to behave exactly as described by the dynamics.
 - ▶ We only require an ϵ -fraction of the agents to improve their strategy when they are above $(1 + \epsilon)\bar{l}$
 - ▶ One might chose λ in a different way, e. g. the prob. to change $\frac{l_i - l_j}{l_i}$
- ▶ In the multicommodity case

Some remarks

- ▶ This analysis is fairly robust – agents are not required to behave exactly as described by the dynamics.
 - ▶ We only require an ϵ -fraction of the agents to improve their strategy when they are above $(1 + \epsilon)\bar{l}$
 - ▶ One might chose λ in a different way, e. g. the prob. to change $\frac{l_i - l_j}{l_i}$
- ▶ In the multicommodity case
 - ▶ (non-unique) Nash equilibria are *essentially evolutionary stable* and the replicator dynamics converges against one of them

Some remarks

- ▶ This analysis is fairly robust – agents are not required to behave exactly as described by the dynamics.
 - ▶ We only require an ϵ -fraction of the agents to improve their strategy when they are above $(1 + \epsilon)\bar{l}$
 - ▶ One might choose λ in a different way, e.g. the prob. to change $\frac{l_i - l_j}{l_i}$
- ▶ In the multicommodity case
 - ▶ (non-unique) Nash equilibria are *essentially evolutionary stable* and the replicator dynamics converges against one of them
 - ▶ we can show an upper bound of $\mathcal{O}(\epsilon^{-3} \ln l_{\max}/l^*)$ using weaker estimates.

Conclusion

- ▶ For strictly increasing latency functions, Wardrop equilibria are evolutionary stable.
- ▶ Solutions of the replicator dynamics converge towards restricted Wardrop equilibria.
- ▶ The time until almost all are almost happy is bounded by
 - ▶ $\mathcal{O}(\epsilon^{-3} \cdot \ln \frac{l_{\max}}{l^*})$ for single commodity networks
 - ▶ $\mathcal{O}(\epsilon^{-2} \cdot \ln \frac{l_{\max}}{l^*})$ for multicommodity parallel links.
 - ▶ $\mathcal{O}(\epsilon^{-3} \cdot \ln \frac{l_{\max}}{l^*})$ for general multicommodity networks, and
 - ▶ $\Omega(\epsilon^{-2} \cdot \ln \frac{l_{\max}}{l^*})$ for all of these.

Open Questions





- ▶ How can we improve the bound for the multi-commodity case?

Open Questions

- ▶ How can we improve the bound for the multi-commodity case?
- ▶ What happens in a discrete process?

Open Questions

- ▶ How can we improve the bound for the multi-commodity case?
- ▶ What happens in a discrete process?
- ▶ How can we use this to implement routing algorithms?

-  Simon Fischer and Berthold Vöcking.
On the evolution of selfish routing.
In Proc. of ESA 2004, 2004.
-  J. Maynard Smith and G. R. Price.
The logic of animal conflict.
Nature, 246:15–18, 1973.
-  Robert W. Rosenthal.
A class of games possessing pure-strategy Nash equilibria.
International Journal of Game Theory, 2:65–67, 1973.
-  Jörgen W. Weibull.
Evolutionary Game Theory.
MIT press, 1995.

Thank you for your attention!